

Laser-induced cavitation bubbles: Mathematical models & simulations

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Joint work with Marica Pelanti at ENSTA, Paris Tech, France

In the memory of our neighbor

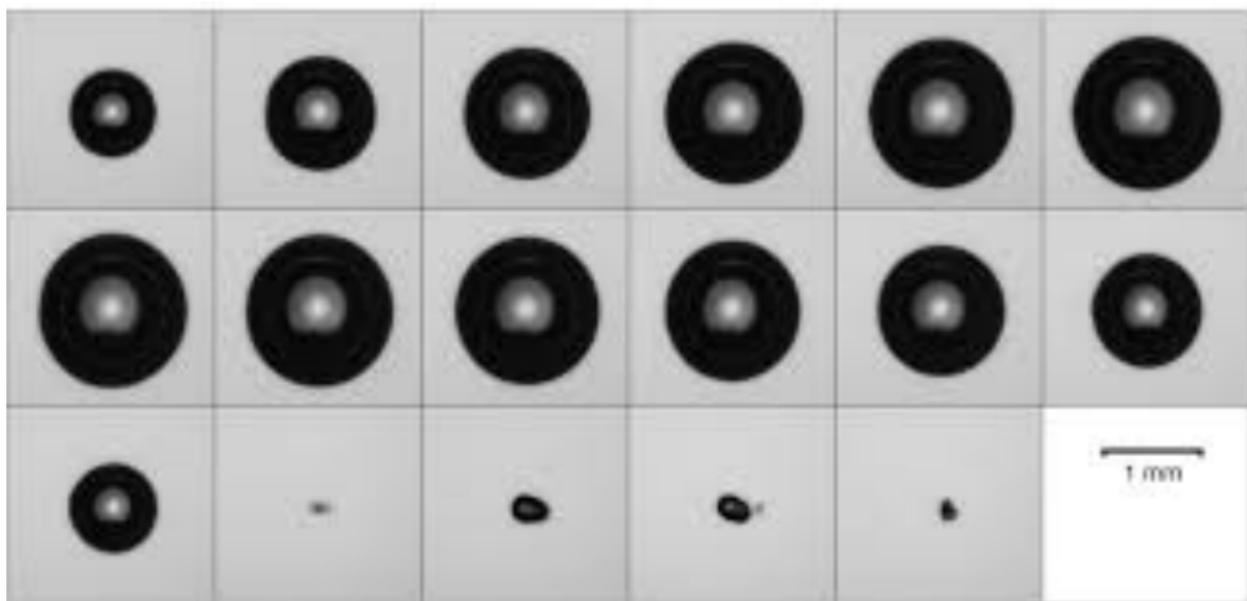
Professor Jaw-Yen Yang

NTU Qin-Tien Faculty Residence Bldg.

Model scientific problem

Expansion & collapse of laser-generated bubble

- Experimental results: Müller *et al.* (CAF 2009)



Bubble radius: Time history

Experiment vs. Keller-Miksis model

S. Müller et al./Computers & Fluids 38 (2009) 1850–1862

1855

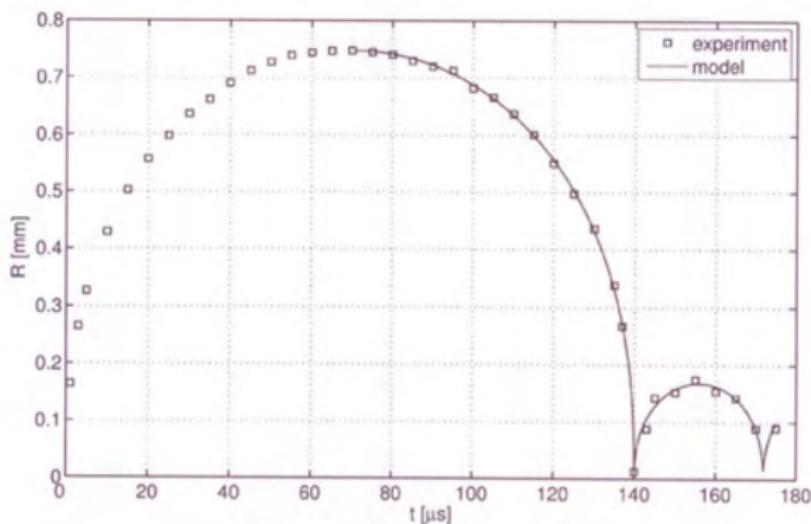
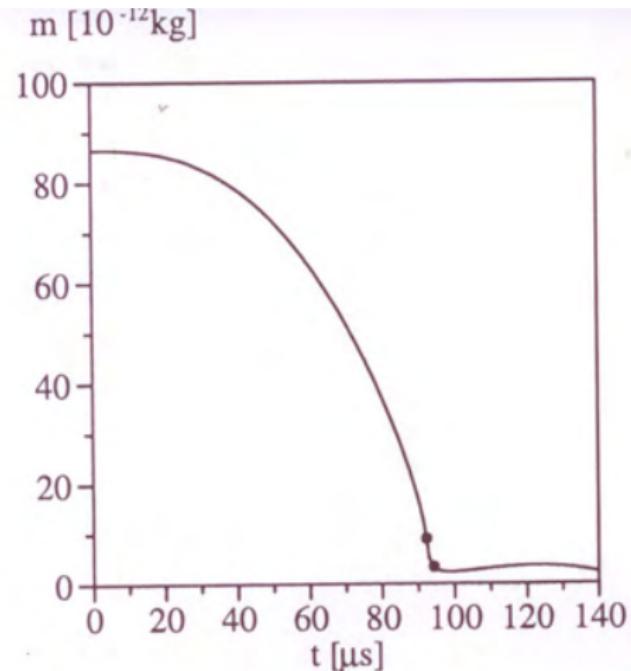


Fig. 3. The points (□) give the experimentally measured bubble radii as a function of time. The solid curve starting at maximum radius presents a numerical solution of the Keller-Miksis model with its parameters fitted to the experiment as described in the text.

Vapor mass: Time history

Akhatov *et al.* (ETFS 2002): Spherically symmetric compressible flow model with **heat conduction & phase transition**



Laser bubble problem: Scientific issues

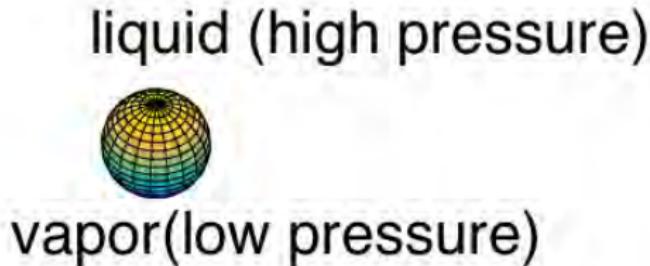
Modelling & simulation of liquid-vapor flow

1. Bubble collapse: Condensation phase
2. Bubble rebound: Evaporation phase:

Laser bubble problem: Benchmark test

Zein *et al.*, Intl J. Numer. Meth. 2013

- High pressure compression of spherically-symmetric water vapor (or water vapor-inert gas) bubble in liquid



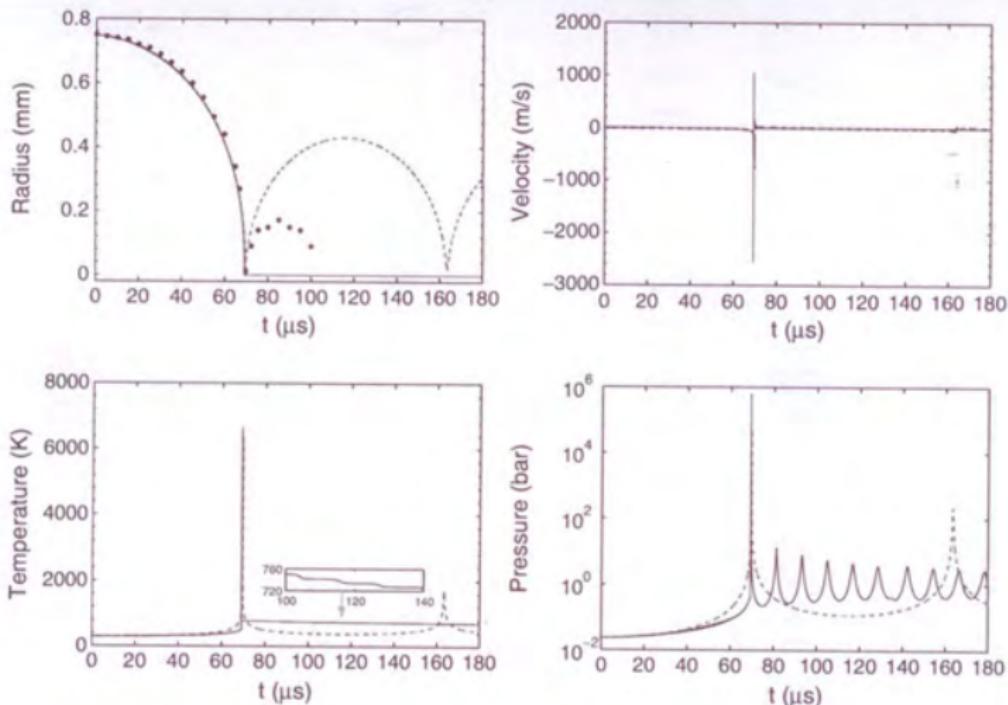
Mathematical models: Compressible 2-phase flow

Models of choice for laser bubble problems include

1. 7-equation model
2-velocity, 2-pressure, 2-temperature, & 2-entropy
2. 6-equation model (*Zein et al.* & *Müller et al.*)
1-velocity, 2-pressure, 2-temperature, & 2-entropy
3. 5-equation model (*Müller et al.*)
1-velocity, 1-pressure, 2-temperature, & 2-entropy
4. 4-equation model
1-velocity, 1-pressure, 1-temperature, & 2-entropy
5. 3-equation model
1-velocity, 1-pressure, 1-temperature, & 1-entropy

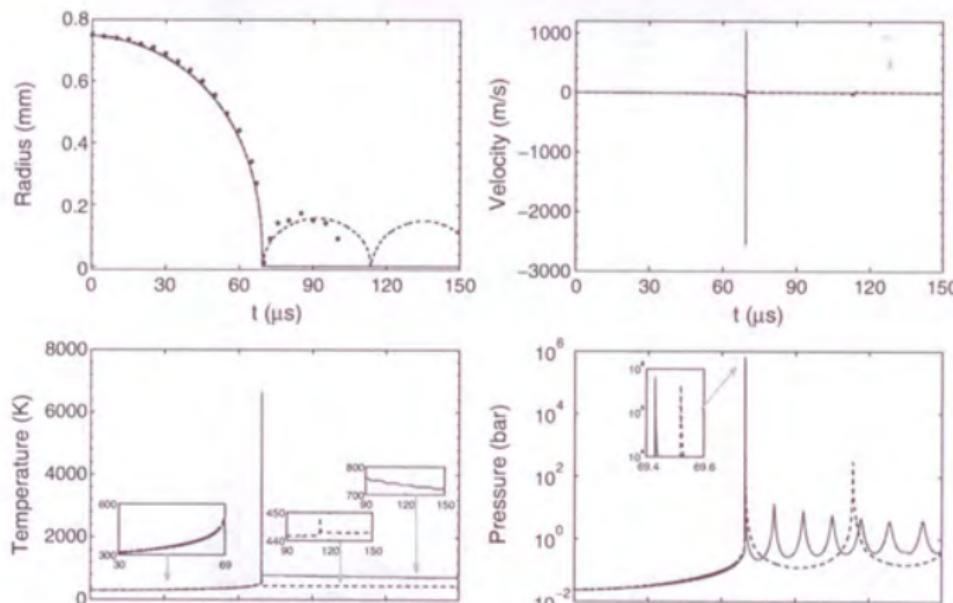
Previous result: Vapor bubble case

Zein *et al.* 2013: 6-equation for 2-phase flow with & without phase transition (**no rebound after collapse with phase change**)



Previous result: Gas-vapor bubble case

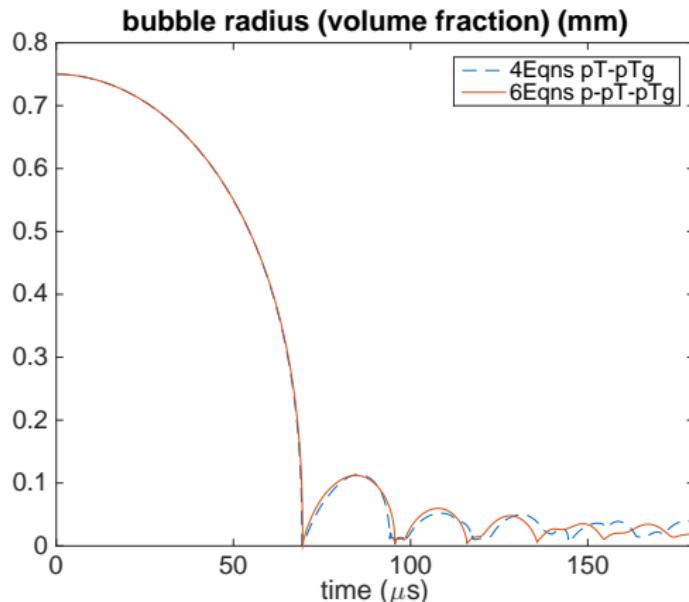
Zein et al. 2013: variant 6-equation for 3-phase flow with non-condensable gas (rebounds occur but disagree with experiment)



Present results: Vapor bubble case

Phase transition results of 2 different models for 2-phase flow

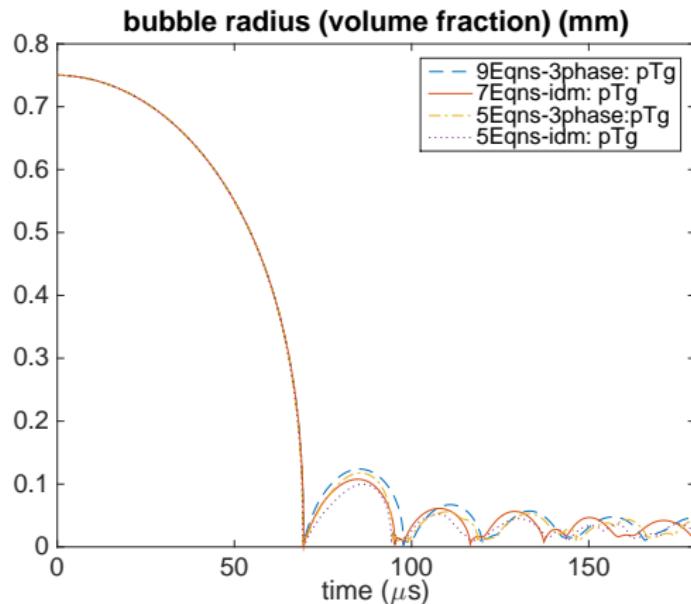
- Rebounds exist with decay of magnitude in time (**agree with experiment qualitatively**)



Present results: Gas-vapor bubble case

Phase transition results of 4 different models for 3-phase flow

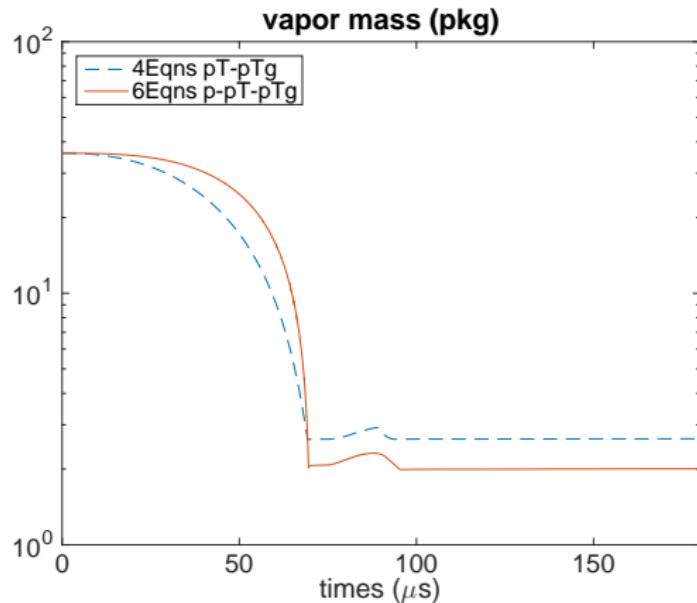
- Rebounds exist with decay of magnitude in time (**agree with experiment qualitatively**)
- Noncondensable O_2 with $\alpha_a = 10^{-2}$ included



Present result: Vapor bubble case

Phase transition results of 2 different models for 2-phase flow

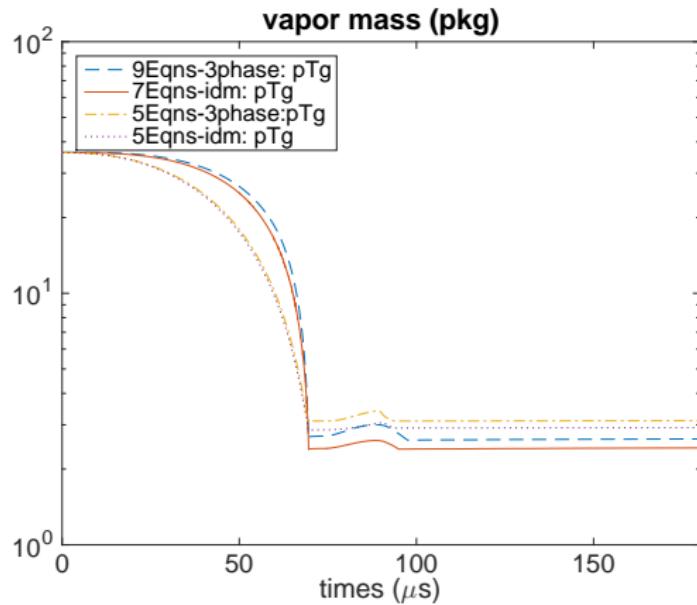
- Vapor mass decreases due to bubble collapse & increases due to rebound (**agree with Akhatov's prediction qualitatively**)



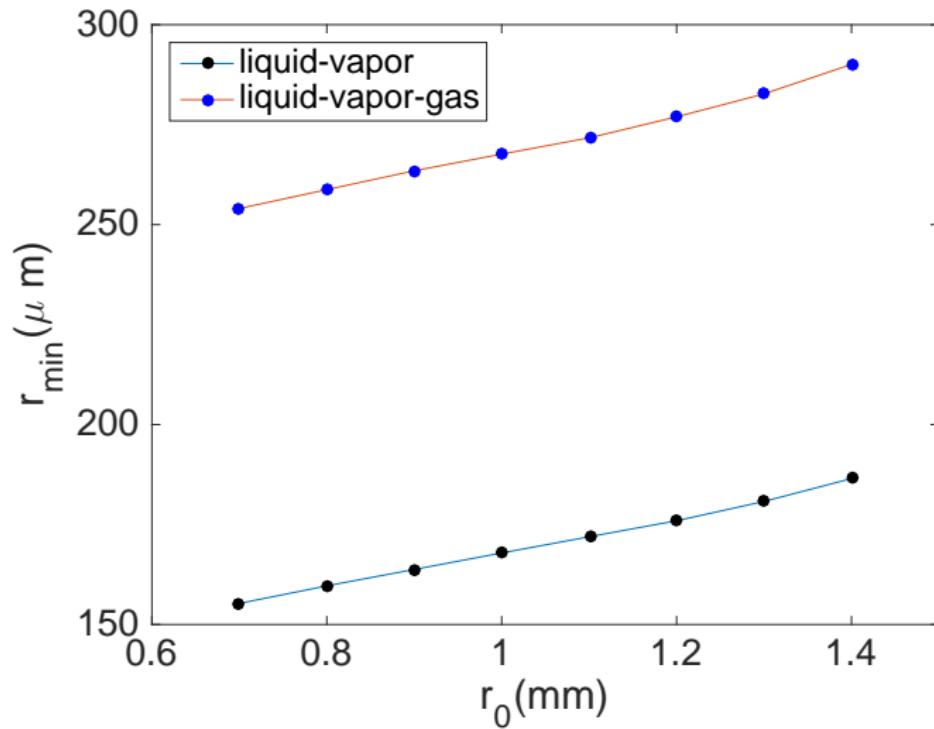
Present result: Gas-vapor bubble case

Phase transition results of 4 different models for 3-phase flow

- Gas mass decreases due to bubble collapse & increases due to rebound (**agree with Akhatov's prediction qualitatively**)



Initial bubble size vs. minimum bubble radius



Laser bubble problem: CPU timing

Machine: Mac with Intel(R) Xeon(R) E5-1620 v2@3.70GHz

2-phase	Mesh/ R_0	CPUs	3-phase	Mesh/ R_0	CPUs	
4Eqns	125	3122	5Eqns	125	7703	
	250	19518		250	28868	
	500	72487		500	91786	
6Eqns	125	4192	5Eqns-idm	125	4888	
	250	24937		250	14492	
	500	73649		500	56994	
		9Eqns	125	6102		
			250	26876		
			500	101929		
		7Eqns-idm	125	4625		
			250	18362		
			500	73366		

Talk outline

Objective: Talk simple model & basic idea in numerics

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1. Mathematical model

- 1-velocity, 1-pressure, 1-temperature, & 2-entropy model
 - 4-equation model for 2-phase flow & its variant for 3-phase flow
- 1-velocity, 2-pressure, 2-temperature, & 2-entropy model
(referred to M. Pelanti's talk)
 - 6-equation model for 2-phase flow & its variant for 3-phase flow

2. Numerical method

- Solver for thermo-chemical phase-change equation

Talk outline

Objective: Talk simple model & basic idea in numerics

1. Mathematical model

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2. Numerical method

- Solver for thermo-chemical phase-change equation

Work in progress

Compressible 2-phase flow: 4-equation model

Consider 1-velocity, 1-pressure, & 1-temperature compressible 2-phase flow model with phase transition of form

$$\begin{aligned}\partial_t \rho + \nabla \cdot (\rho \vec{u}) &= 0 \\ \partial_t (\rho \vec{u}) + \nabla \cdot \left(\rho \vec{u} \otimes \vec{u} + p \bar{\bar{I}} \right) &= 0 \\ \partial_t (\rho E) + \nabla \cdot (\rho E \vec{u} + p \vec{u}) &= 0 \\ \partial_t (\rho Y_1) + \nabla \cdot (\rho Y_1 \vec{u}) &= \dot{m}\end{aligned}$$

ρ : mixture density, \vec{u} : velocity

p : mixture pressure, E : total energy

Y_k : mass fraction for phase k ($Y_1 + Y_2 = 1$)

\dot{m} : mass transfer term

Compressible 2-phase flow: 4-equation model

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Model closure: isobaric-isothermal, i.e., p & T equilibrium without phase transition

4-equation model: Mass transfer

Assume mass transfer via thermo-chemical relaxation:

- Gibbs free energy based

$$\dot{m} = \rho \mu_g (g_2 - g_1)$$

- Mass fraction based

$$\dot{m} = \rho \mu_Y (Y^* - Y_1)$$

Relaxation parameter μ_k , $k = g, Y$ controls rate of “phase transition”, e.g., vaporization or condensation of liquid & vapor

Downar-Zapolski *et al.* : Empirical fit

$$\mu_Y = a \alpha^b \phi^c, \quad \varphi = \left| \frac{p_{\text{sat}} - p}{p_c - p_{\text{sat}}} \right|$$

HRM: Model as $\mu = 0$, $\nu \rightarrow \infty$ & $\theta \rightarrow \infty$

Assume frozen chemical relaxation $\mu = 0$, HRM in mechanical-thermal limit as $\nu \rightarrow \infty$ & $\theta \rightarrow \infty$ reads (Saurel *et al.* 2008, Flåtten *et al.* 2010)

$$\begin{aligned}\partial_t \rho + \nabla \cdot (\rho \vec{u}) &= 0 \\ \partial_t (\rho \vec{u}) + \nabla \cdot \left(\rho \vec{u} \otimes \vec{u} + p \vec{\bar{I}} \right) &= 0 \\ \partial_t E + \nabla \cdot (E \vec{u} + p \vec{u}) &= 0 \\ \partial_t (\rho Y_1) + \nabla \cdot (\rho Y_1 \vec{u}) &= 0\end{aligned}$$

Mechanical-thermal equilibrium speed of sound satisfies

$$\frac{1}{\rho c_{pT}^2} = \frac{1}{\rho c_p^2} + \textcolor{blue}{T} \left(\frac{\Gamma_2}{\rho_2 c_2^2} - \frac{\Gamma_1}{\rho_1 c_1^2} \right)^2 \Bigg/ \left(\frac{1}{\alpha_1 \rho_1 c_{p1}} + \frac{1}{\alpha_2 \rho_2 c_{p2}} \right)$$

Homogeneous relaxation model (HRM)

Consider HRM for 2-phase flow of form

$$\partial_t (\alpha_1 \rho_1) + \nabla \cdot (\alpha_1 \rho_1 \vec{u}) = \mu (g_2 - g_1)$$

$$\partial_t (\alpha_2 \rho_2) + \nabla \cdot (\alpha_2 \rho_2 \vec{u}) = \mu (g_1 - g_2)$$

$$\partial_t (\rho \vec{u}) + \nabla \cdot (\rho \vec{u} \otimes \vec{u}) + \nabla (\alpha_1 p_1 + \alpha_2 p_2) = 0$$

$$\partial_t (\alpha_1 E_1) + \nabla \cdot (\alpha_1 E_1 \vec{u} + \alpha_1 p_1 \vec{u}) + \mathcal{B}(q, \nabla q) =$$

$$\nu p_I (p_2 - p_1) + \theta T_I (T_2 - T_1) + \mu g_I (g_2 - g_1)$$

$$\partial_t (\alpha_2 E_2) + \nabla \cdot (\alpha_2 E_2 \vec{u} + \alpha_2 p_2 \vec{u}) - \mathcal{B}(q, \nabla q) =$$

$$\nu p_I (p_1 - p_2) + \theta T_I (T_1 - T_2) + \mu g_I (g_1 - g_2)$$

$$\partial_t \alpha_1 + \vec{u} \cdot \nabla \alpha_1 = \nu (p_1 - p_2) + \mu v_I (g_1 - g_2)$$

$\mathcal{B}(q, \nabla q)$ is non-conservative product (q : state vector)

$$\mathcal{B} = \vec{u} \cdot [Y_1 \nabla (\alpha_2 p_2) - Y_2 \nabla (\alpha_1 p_1)]$$

$\nu, \theta, \mu \rightarrow \infty$: instantaneous exchanges (relaxation effects)

1. Volume transfer via pressure relaxation: $\nu (p_1 - p_2)$
 - ν expresses rate toward mechanical equilibrium $p_1 \rightarrow p_2$, & is nonzero in all flow regimes of interest
2. Heat transfer via temperature relaxation: $\theta (T_2 - T_1)$
 - θ expresses rate towards thermal equilibrium $T_1 \rightarrow T_2$, & is nonzero only at 2-phase mixture
3. Mass transfer via thermo-chemical relaxation: $\mu (g_2 - g_1)$
 - μ expresses rate towards diffusive equilibrium $g_1 \rightarrow g_2$, & is nonzero only at 2-phase mixture & metastable state

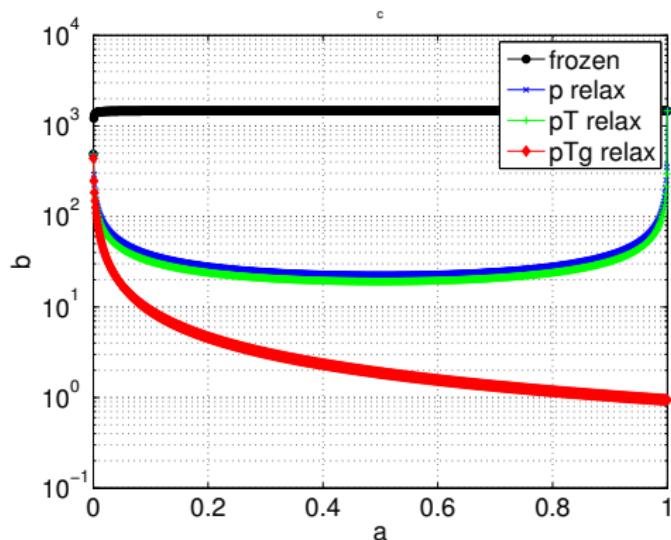
Equilibrium speed of sound

- Sound speeds follow subcharacteristic condition

$$c_{pTg} \leq c_{pT} \leq c_p \leq c_f$$

- Limit of sound speed

$$\lim_{\alpha_k \rightarrow 1} c_f = \lim_{\alpha_k \rightarrow 1} c_p = \lim_{\alpha_k \rightarrow 1} c_{pT} = c_k, \quad \lim_{\alpha_k \rightarrow 1} c_{pTg} \neq c_k$$



4-equation model: Spherically-symmetric case

For laser-induced bubble problem, equations we take are either

$$\partial_t \rho + \partial_V (r^2 \rho u) = 0$$

$$\partial_t (\rho u) + \partial_V (r^2 \rho u^2 + r^2 p) = \frac{2}{r} p$$

$$\partial_t (\rho E) + \partial_V (r^2 \rho Eu + r^2 pu) = 0$$

$$\partial_t (\rho Y_1) + \partial_V (r^2 \rho Y_1 u) = \frac{1}{r^2} \dot{m}$$

where $\partial V = r^2 \partial_r$, or

$$\partial_t \rho + \partial_r (\rho u) = -\frac{2}{r} \rho u$$

$$\partial_t (\rho u) + \partial_r (\rho u^2 + p) = -\frac{2}{r} \rho u^2$$

$$\partial_t (\rho E) + \partial_r (\rho Eu + pu) = -\frac{2}{r} (\rho E + p) u$$

$$\partial_t (\rho Y_1) + \partial_r (\rho Y_1 u) = -\frac{2}{r} \rho Y_1 u + \frac{1}{r^2} \dot{m}$$

Constitutive law

Assume stiffened gas equation of state (SG EOS) with

- Specific volume

$$v_k(p_k, T_k) = \frac{(\gamma_k - 1)C_{v,k}T_k}{p_k + p_{\infty,k}}$$

- Specific internal energy

$$e_k(p_k, T_k) = C_{v,k}T_k \left(\frac{p_k + \gamma_k p_{\infty,k}}{p_k + p_{\infty,k}} \right) + q_k$$

- Entropy

$$s_k(p_k, T_k) = C_{vk} \log \frac{T_k^{\gamma_k}}{(p_k + p_{\infty,k})^{\gamma_k - 1}} + q'_k$$

- Helmholtz free energy $a_k = e_k - T_k s_k$
- Gibbs free energy $g_k = a_k + p_k v_k$

Stiffened gas EOS parameters

Water: liquid- & vapor-phase

Air: oxygen & hydrogen (noncondensable gas)

Parameters/Phase	Liquid	Vapor	O_2	H_2
γ	2.35	1.43	1.4	1.4
p_∞ (Pa)	10^9	0	0	0
q (J/kg)	-11.6×10^3	2030×10^3	0	0
q' (J/(kg · K))	0	-23.4×10^3	0	0
C_v (J/(kg · K))	1816	1040	662	1010

Ref: Zein *et al.*, Intl J. Numer. Meth. 2013

Numerical scheme: Fractional step approach

Write model equation in compact form as

$$\partial_t q + \nabla \cdot f(q) = \psi(q) = \psi_s(q) + \psi_\mu(q)$$

Employ standard fractional step method for numerical approximation, *i.e.*,

1. Solve homogeneous equation **without phase transition**

$$\partial_t q + \nabla \cdot f(q) = 0$$

using state-of-the-art shock-capturing (diffuse-interface) method for hyperbolic conservation laws (**model is hyperbolic**)

2. Solve ODEs with **geometric & phase transition** source terms

$$\partial_t q = \psi_s(q) + \psi_\mu(q)$$

using standard solvers

Model closure: pT equilibrium solution

With stiffened gas EOS, it follows from

$$v = Y_1 v_1(\mathbf{p}, \mathbf{T}) + Y_2 v_2(\mathbf{p}, \mathbf{T}) \quad (v = 1/\rho, v_k = 1/\rho_k)$$

$$e = Y_1 e_1(\mathbf{p}, \mathbf{T}) + Y_2 e_2(\mathbf{p}, \mathbf{T})$$

that we have

$$v = Y_1 \frac{(\gamma_1 - 1)C_{v,1}\mathbf{T}}{\mathbf{p} + p_{\infty,1}} + Y_2 \frac{(\gamma_2 - 1)C_{v,2}\mathbf{T}}{\mathbf{p} + p_{\infty,2}}$$

$$e = Y_1 C_{v,1} \mathbf{T} \left(\frac{\mathbf{p} + \gamma_1 p_{\infty,1}}{\mathbf{p} + p_{\infty,1}} \right) + Y_1 q_1 +$$

$$Y_2 C_{v,2} \mathbf{T} \left(\frac{\mathbf{p} + \gamma_2 p_{\infty,2}}{\mathbf{p} + p_{\infty,2}} \right) + Y_2 q_2$$

yielding **single quadratic equation for \mathbf{p}** (not shown) & explicit computation of \mathbf{T} :

$$\frac{1}{\rho \mathbf{T}} = Y_1 \frac{(\gamma_1 - 1)C_{v1}}{\mathbf{p} + p_{\infty,1}} + Y_2 \frac{(\gamma_2 - 1)C_{v2}}{\mathbf{p} + p_{\infty,2}}$$

Phase change equations: pTg equilibrium solution

Suppose solution states lie in **metastable** region & assume infinite relaxation $\nu \rightarrow \infty$, want to find equilibrium states for p , T , & Y_1 so that $g_1 \rightarrow g_2$, yielding fulfillment of following conditions

1. Saturation condition for pressure p & temperature T

$$\mathcal{G}(p, T) := g_1(p, T) - g_2(p, T) = 0$$

2. Equilibrium condition for specific volume v

$$Y_1 v_1(p, T) + Y_2 v_2(p, T) = v$$

3. Equilibrium condition for internal energy e

$$Y_1 e_1(p, T) + Y_2 e_2(p, T) = e$$

or for specific enthalpy h defined by $h_k = e_k + pv_k$

$$Y_1 h_1(p, T) + Y_2 h_2(p, T) = h$$

pTg equilibrium solution

From saturation condition for equilibrium p & T :

$$\mathcal{G}(p, T) = 0$$

& equilibrium conditions 2 & 3 above: i.e., either

$$\mathcal{H}(p, T) = \frac{v - v_2(p, T)}{v_1(p, T) - v_2(p, T)} - \frac{e - e_2(p, T)}{e_1(p, T) - e_2(p, T)} = 0$$

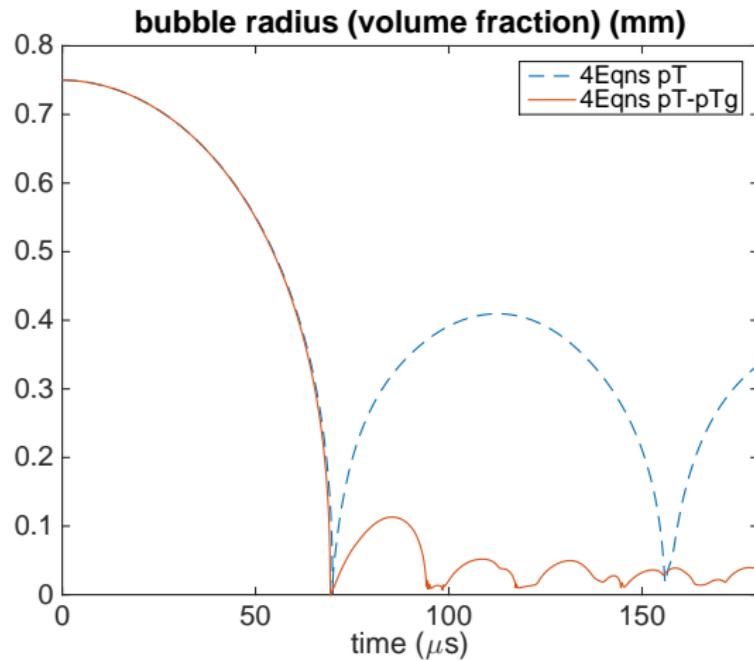
or

$$\mathcal{H}(p, T) = \frac{v - v_2(p, T)}{v_1(p, T) - v_2(p, T)} - \frac{h(p) - h_2(p, T)}{h_1(p, T) - h_2(p, T)} = 0$$

we have 2 equations $\mathcal{G} = 0$ & $\mathcal{H} = 0$ for 2 unknowns p & T
which can be solved by employing root-finding method
iteratively

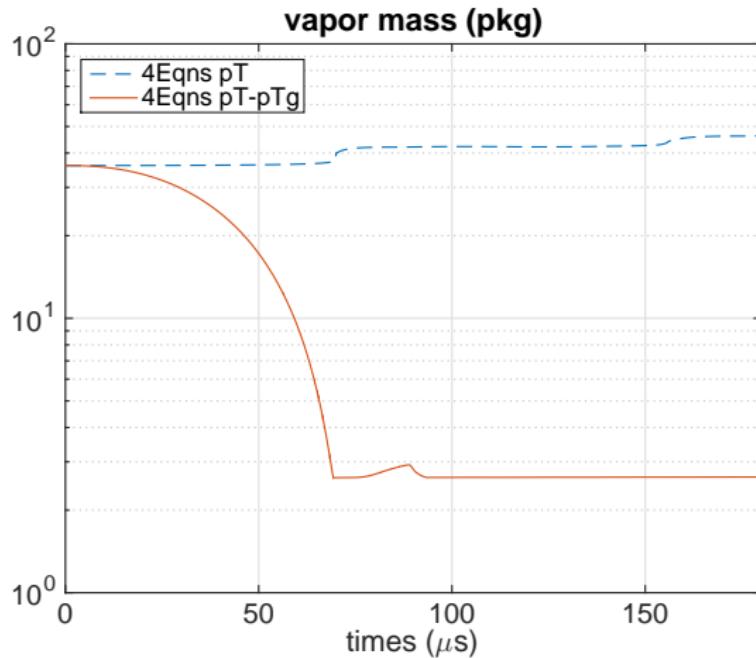
Benchmark laser bubble test: Bubble radius

Less rebounds without phase transition



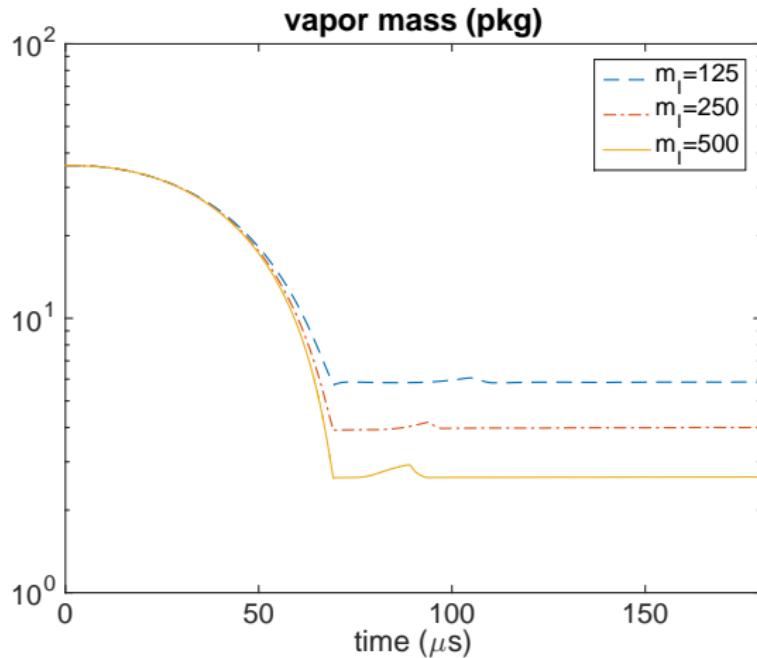
Benchmark laser bubble test: Vapor mass

Vapor mass increases without phase transition



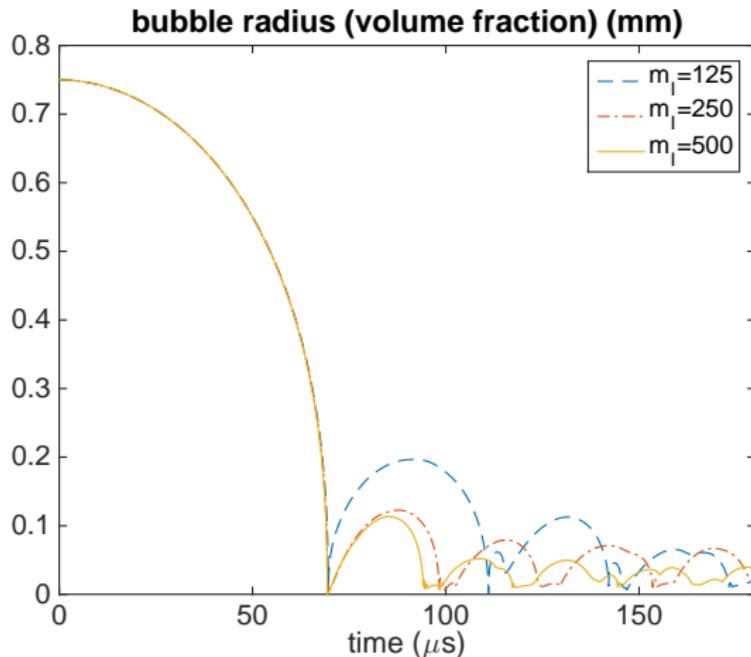
Vapor mass: Mesh refinement test

Vapor mass decreases more as mesh is refined



Bubble radius: Mesh refinement test

More rebounds as mesh is refined with smaller bubble-radius amplitude



Compressible 3-phase flow: 5-equation model

Extension of 4-equation p - T model from 2-phase to 3-phase flow takes form

$$\partial_t (\alpha_v \rho_v) + \nabla \cdot (\alpha_v \rho_v \vec{u}) = \dot{m}$$

$$\partial_t (\alpha_l \rho_l) + \nabla \cdot (\alpha_l \rho_l \vec{u}) = -\dot{m}$$

$$\partial_t (\alpha_a \rho_a) + \nabla \cdot (\alpha_a \rho_a \vec{u}) = 0 \quad (\text{non-condensable})$$

$$\partial_t (\rho \vec{u}) + \nabla \cdot \left(\rho \vec{u} \otimes \vec{u} \right) + p \bar{\bar{I}} = 0$$

$$\partial_t (\rho E) + \nabla \cdot (\rho E \vec{u} + p \vec{u}) = 0$$

With given EOS for each phase, mixture pressure $\textcolor{blue}{p}$ & temperature $\textcolor{blue}{T}$ can be computed from

$$v = Y_v v_v(\textcolor{blue}{p}, \textcolor{blue}{T}) + Y_l v_l(\textcolor{blue}{p}, \textcolor{blue}{T}) + Y_a v_a(\textcolor{blue}{p}, \textcolor{blue}{T})$$

$$e = Y_v e_v(\textcolor{blue}{p}, \textcolor{blue}{T}) + Y_l e_l(\textcolor{blue}{p}, \textcolor{blue}{T}) + Y_a e_a(\textcolor{blue}{p}, \textcolor{blue}{T})$$

Mass transfer term \dot{m} takes same relaxation form as before

Phase change equations: pTg solution

Suppose solution state lies in **metastable** region & assume infinite relaxation $\nu \rightarrow \infty$, want to find equilibrium states for p , T , & Y_v so that $g_v \rightarrow g_l$, yielding fulfillment of following conditions

1. Saturation condition for pressure p & temperature T

$$\mathcal{G}(p, T) := g_v(p, T) - g_l(p, T) = 0$$

2. Equilibrium condition for specific volume v

$$Y_v v_v(p, T) + Y_l v_l(p, T) + Y_a v_a(p, T) = v$$

3. Equilibrium condition for specific enthalpy h

$$Y_v h_v(p, T) + Y_l h_l(p, T) + Y_a h_a(p, T) = h$$

4. Equilibrium condition for mass fraction $Y_v + Y_l$

$$Y_v + Y_l = 1 - Y_a$$

3-phase 5-equation model: pTg solution

From saturation condition for equilibrium p & T :

$$\mathcal{G}(\mathbf{p}, \mathbf{T}) = 0$$

& equilibrium conditions 2, 3, & 4 above:

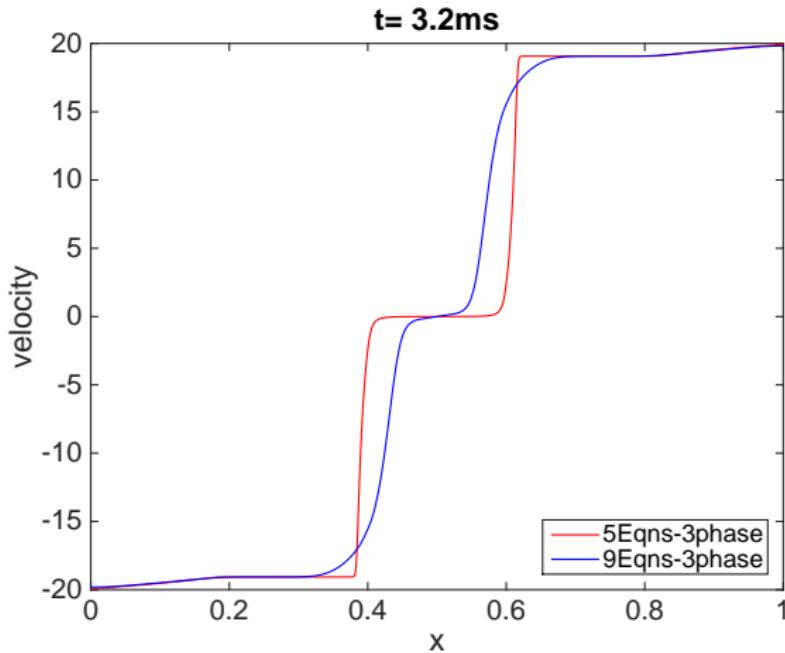
$$\begin{aligned}\mathcal{H}(\mathbf{p}, \mathbf{T}) := & \frac{v - Y_a v_a(\mathbf{p}, \mathbf{T}) - (1 - Y_a) v_l(\mathbf{p}, \mathbf{T})}{v_v(\mathbf{p}, \mathbf{T}) - v_l(\mathbf{p}, \mathbf{T})} - \\ & \frac{h(\mathbf{p}, \mathbf{T}) - Y_a h_a(\mathbf{p}, \mathbf{T}) - (1 - Y_a) h_l(\mathbf{p}, \mathbf{T})}{h_v(\mathbf{p}, \mathbf{T}) - h_l(\mathbf{p}, \mathbf{T})} = 0\end{aligned}$$

we have 2 equations for 2 unknowns p & T which can be solved by employing root-finding method iteratively

Cavitation test: Numerical validation

Velocity at time $t = 3.2\text{ms}$

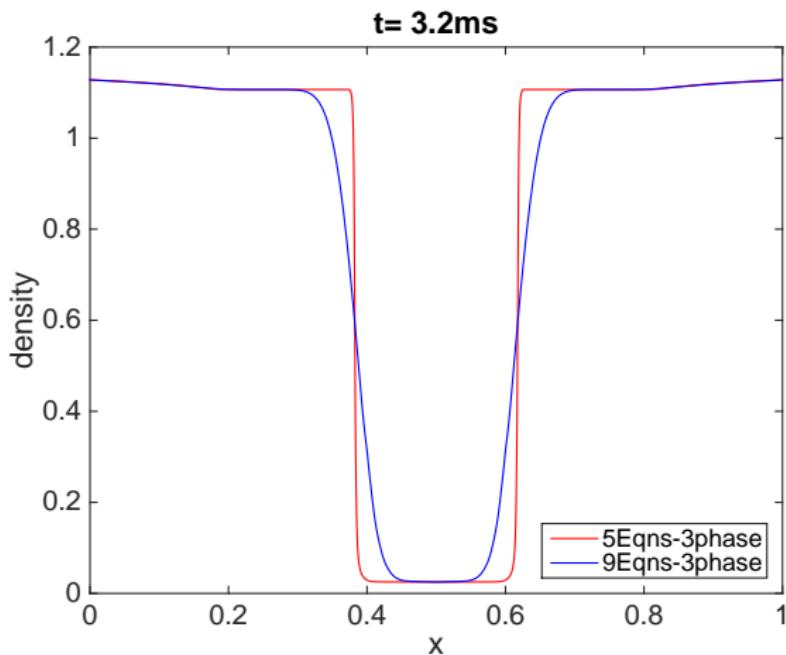
- Existence of 4 (2 rerefaction & 2 evaporation) wave structures



Cavitation test: Numerical validation

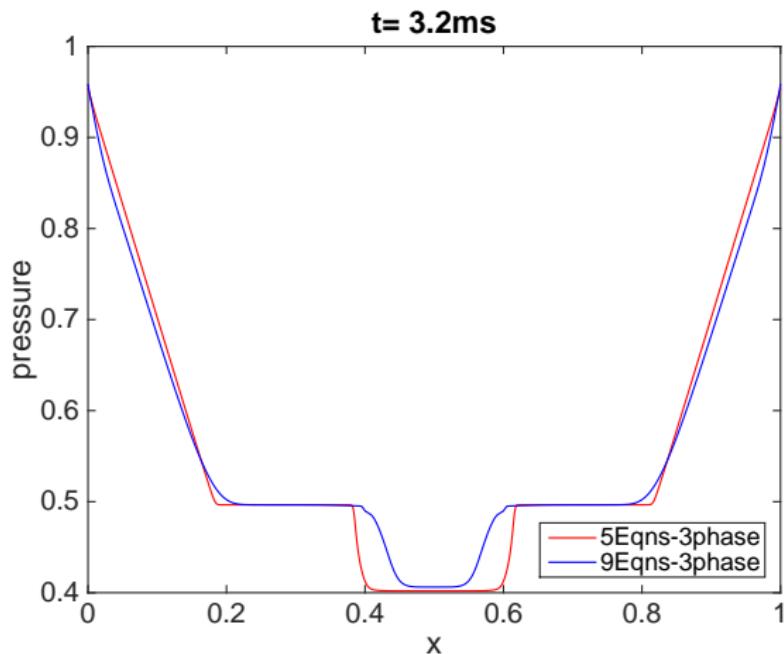
Total density at time $t = 3.2\text{ms}$

- 5-equation model gives sharper resolution for evaporation wave than 9-equation model



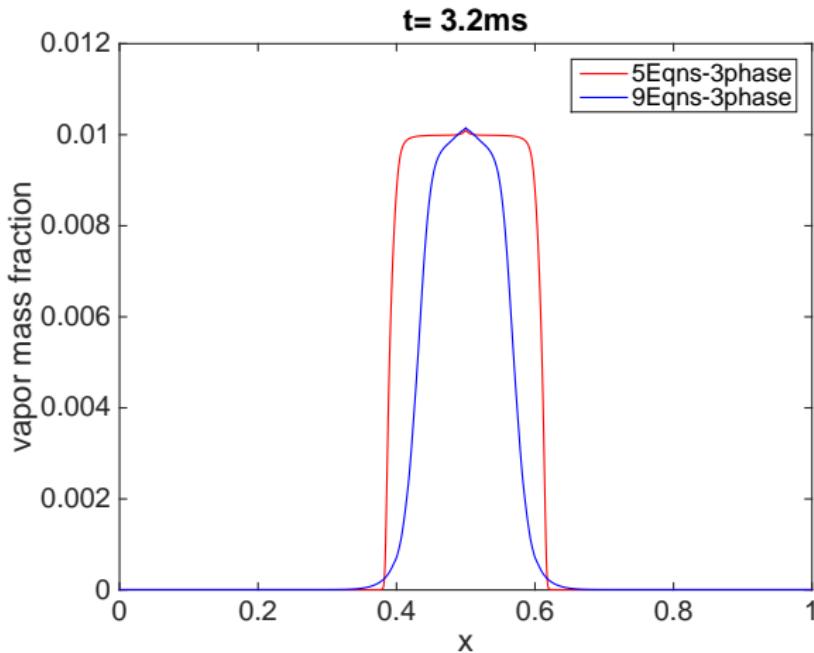
Cavitation test: Numerical validation

Pressure at time $t = 3.2\text{ms}$



Cavitation test: Numerical validation

Vapor mass fraction at time $t = 3.2\text{ms}$



3-phase flow: 5-equation ideal-mixing model

Assume **ideal mixing** of **air & vapor**, i.e., each component behaves as ideal gas alone & occupies entire gas mixture

Ideal-mixing (2-phase) version of 3-phase 5-equation model is

$$\partial_t (\alpha_l \rho_l) + \nabla \cdot (\alpha_l \rho_l \vec{u}) = \dot{m}$$

$$\partial_t (\alpha_g \rho_v) + \nabla \cdot (\alpha_g \rho_v \vec{u}) = -\dot{m}$$

$$\partial_t (\alpha_g \rho_a) + \nabla \cdot (\alpha_g \rho_a \vec{u}) = 0 \quad (\text{non-condensable})$$

$$\partial_t (\rho \vec{u}) + \nabla \cdot \left(\rho \vec{u} \otimes \vec{u} \right) + p \bar{\bar{I}} = 0$$

$$\partial_t (\rho E) + \nabla \cdot (\rho E \vec{u} + p \vec{u}) = 0$$

Mixture density ρ & gas mass fraction Y_g are defined by

$$\rho = \alpha_l \rho_l + \alpha_g \rho_g, \quad \rho_g = \rho_a + \rho_v$$

$$Y_g = Y_v + Y_a = \frac{\alpha_g \rho_g}{\alpha_l \rho_l + \alpha_g \rho_g}, \quad \alpha_l + \alpha_g = 1$$

Model closure: pT equilibrium solution

Given Y_g , v , & e , model admit single $\textcolor{blue}{p}$ & $\textcolor{blue}{T}$ fulfilling

$$(1 - Y_g) v_l(\textcolor{blue}{p}, \textcolor{blue}{T}) + Y_g \textcolor{red}{v}_g(\textcolor{blue}{p}, \textcolor{blue}{T}) = v$$

$$(1 - Y_g) e_l(\textcolor{blue}{p}, \textcolor{blue}{T}) + Y_g \textcolor{red}{e}_g(\textcolor{blue}{p}, \textcolor{blue}{T}) = e$$

with EOS parameters for v_g & e_g known a priori

Aforementioned pT equilibrium solver for 2-phase 4-equation model is applicable here

5-equation ideal-mixing: EOS parameters

Assume SG EOS for each fluid phase k , $k = l, v, a$

Assume $T_g = T_v = T_a$ & $p_g = p_v + p_a$, we have

$$C_{v,g} = \frac{\rho_v}{\rho_g} C_{v,v} + \frac{\rho_a}{\rho_g} C_{v,a}$$

$$q_g = \frac{\rho_v}{\rho_g} q_v + \frac{\rho_a}{\rho_g} q_a$$

$$p_{\infty,g} = p_{\infty,v} + p_{\infty,a}$$

$$\gamma_g C_{v,g} = \frac{\rho_v}{\rho_g} \gamma_v C_{v,v} + \frac{\rho_a}{\rho_g} \gamma_a C_{v,a}$$

5-equation ideal-mixing: pTg equilibrium solution

Given v , e , & Y_a , want to find equilibrium states for p , T , & Y_v so that following conditions are satisfied

1. Saturation condition for pressure p & temperature T

$$\mathcal{G}(p, T) := g_l(p, T) - g_v(p, T) = 0$$

2. Equilibrium condition for specific volume v

$$(1 - Y_a - Y_v) v_l(p, T) + (Y_a + Y_v) v_g(p, T) = v$$

3. Equilibrium condition for specific enthalpy h

$$(1 - Y_a - Y_v) h_l(p, T) + (Y_a + Y_v) h_g(p, T) = h$$

5-equation ideal-mixing model: binary diffusion

With **binary diffusion** included, 3-phase 5-equation model with ideal mixings reads

$$\partial_t (\alpha_l \rho_l) + \nabla \cdot (\alpha_l \rho_l \vec{u}) = \dot{m}$$

$$\partial_t (\alpha_g \rho_v) + \nabla \cdot (\alpha_g \rho_v \vec{u}) = -\dot{m} + \nabla \cdot \left(\alpha_g \rho_g \varepsilon_{va} \nabla \left(\frac{\rho_v}{\rho_g} \right) \right)$$

$$\partial_t (\alpha_g \rho_a) + \nabla \cdot (\alpha_g \rho_a \vec{u}) = \nabla \cdot \left(\alpha_g \rho_g \varepsilon_{va} \nabla \left(\frac{\rho_a}{\rho_g} \right) \right)$$

$$\partial_t (\rho \vec{u}) + \nabla \cdot \left(\rho \vec{u} \otimes \vec{u} \right) + p \bar{\bar{I}} = 0$$

$$\partial_t (\rho E) + \nabla \cdot (\rho E \vec{u} + p \vec{u}) = 0$$

ε_{va} : binary diffusion coefficient

Employ fractional step approach for numerical treatment of binary diffusion terms

4-phase flow: 6-equation ideal-mixing model

In problems with 2 different non-condensable gas, say O_2 & H_2 , 4-phase flow model with ideal-mixing takes

$$\partial_t (\alpha_l \rho_l) + \nabla \cdot (\alpha_l \rho_l \vec{u}) = \dot{m}$$

$$\partial_t (\alpha_g \rho_v) + \nabla \cdot (\alpha_g \rho_v \vec{u}) = -\dot{m}$$

$$\partial_t (\alpha_g \rho_{a_1}) + \nabla \cdot (\alpha_g \rho_{a_1} \vec{u}) = 0 \quad (\text{non-condensable})$$

$$\partial_t (\alpha_g \rho_{a_2}) + \nabla \cdot (\alpha_g \rho_{a_2} \vec{u}) = 0 \quad (\text{non-condensable})$$

$$\partial_t (\rho \vec{u}) + \nabla \cdot \left(\rho \vec{u} \otimes \vec{u} \right) + p \bar{\bar{I}} = 0$$

$$\partial_t (\rho E) + \nabla \cdot (\rho E \vec{u} + p \vec{u}) = 0$$

Mixture density ρ & gas mass fraction Y_g are defined by

$$\rho = \alpha_l \rho_l + \alpha_g \rho_g, \quad \rho_g = \rho_v + \rho_{a_1} + \rho_{a_2}$$

$$Y_g = Y_v + Y_{a_1} + Y_{a_2} = \frac{\alpha_g \rho_g}{\alpha_l \rho_l + \alpha_g \rho_g}, \quad \alpha_l + \alpha_g = 1$$

6-equation ideal-mixing: EOS parameters

Assume SG EOS for each fluid phase k , $k = l, v, a_1, a_2$

Assume $T_g = T_v = T_{a_1} = T_{a_2}$ & $p_g = p_v + p_{a_1} + p_{a_2}$, we have

$$C_{v,g} = \frac{\rho_v}{\rho_g} C_{v,v} + \frac{\rho_{a_1}}{\rho_g} C_{v,a_1} + \frac{\rho_{a_2}}{\rho_g} C_{v,a_2}$$

$$q_g = \frac{\rho_v}{\rho_g} q_v + \frac{\rho_{a_1}}{\rho_g} q_{a_1} + \frac{\rho_{a_2}}{\rho_g} q_{a_2}$$

$$p_{\infty,g} = p_{\infty,v} + p_{\infty,a_1} + p_{\infty,a_2}$$

$$\gamma_g C_{v,g} = \frac{\rho_v}{\rho_g} \gamma_v C_{v,v} + \frac{\rho_{a_1}}{\rho_g} \gamma_{a_1} C_{v,a_1} + \frac{\rho_{a_2}}{\rho_g} \gamma_{a_2} C_{v,a_2}$$

Analogously, EOS parameters for mixture of $m \geq 2$ different non-condensable gas can be defined easily

6-equation ideal-mixing: pTg equilibrium solution

Given v , e , Y_{a_1} , & Y_{a_2} , want to find equilibrium states for p , T , & Y_v so that following conditions are satisfied

1. Saturation condition for pressure p & temperature T

$$\mathcal{G}(p, T) := g_l(p, T) - g_v(p, T) = 0$$

2. Equilibrium condition for specific volume v

$$(1 - Y_{a_1} - Y_{a_2} - Y_v) v_l(p, T) + (Y_{a_1} + Y_{a_2} + Y_v) v_g(p, T) = v$$

3. Equilibrium condition for specific enthalpy h

$$(1 - Y_{a_1} - Y_{a_2} - Y_v) h_l(p, T) + (Y_{a_1} + Y_{a_2} + Y_v) h_g(p, T) = h$$

5-phase flow: 7-equation ideal-mixing model

In problems with 2 different non-condensable gas, say O_2 & H_2 , & additional solid or fluid-like phase, 5-phase flow model with ideal-mixing for gas & immiscible for other phase takes

$$\partial_t (\alpha_l \rho_l) + \nabla \cdot (\alpha_l \rho_l \vec{u}) = \dot{m}$$

$$\partial_t (\alpha_g \rho_v) + \nabla \cdot (\alpha_g \rho_v \vec{u}) = -\dot{m}$$

$$\partial_t (\alpha_{g1} \rho_{a1}) + \nabla \cdot (\alpha_{g1} \rho_{a1} \vec{u}) = 0 \quad (\text{non-condensable})$$

$$\partial_t (\alpha_{g2} \rho_{a2}) + \nabla \cdot (\alpha_{g2} \rho_{a2} \vec{u}) = 0 \quad (\text{non-condensable})$$

$$\partial_t (\alpha_s \rho_s) + \nabla \cdot (\alpha_s \rho_s \vec{u}) = 0 \quad (\text{solid phase})$$

$$\partial_t (\rho \vec{u}) + \nabla \cdot \left(\rho \vec{u} \otimes \vec{u} \right) + p \vec{\bar{I}} = 0$$

$$\partial_t (\rho E) + \nabla \cdot (\rho E \vec{u} + p \vec{u}) = 0$$

Phase transition closure ?

Bubbly flow in liquid

Iordanski-Kogarko-Wijngaarden model for bubbly flow in liquid takes

$$\partial_t \rho + \partial_x (\rho u) = 0$$

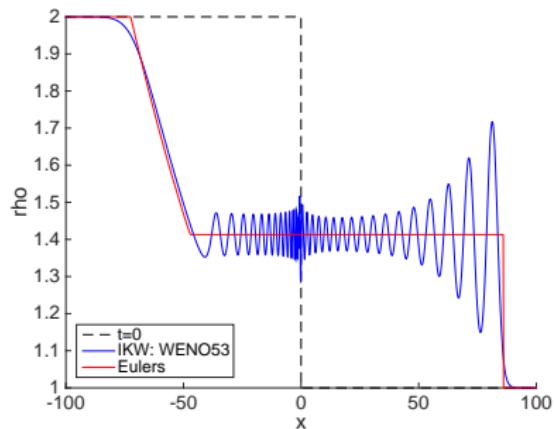
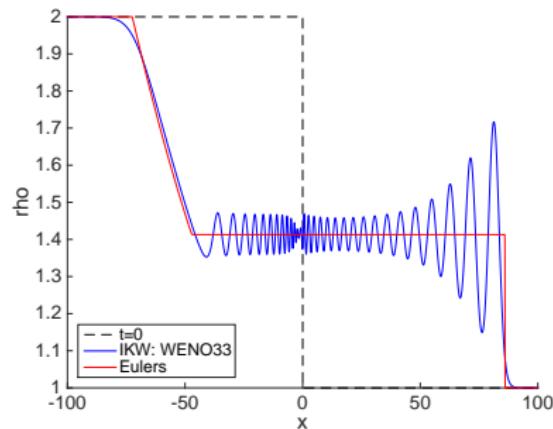
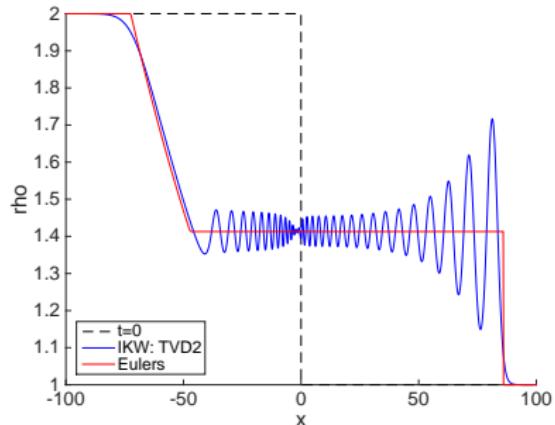
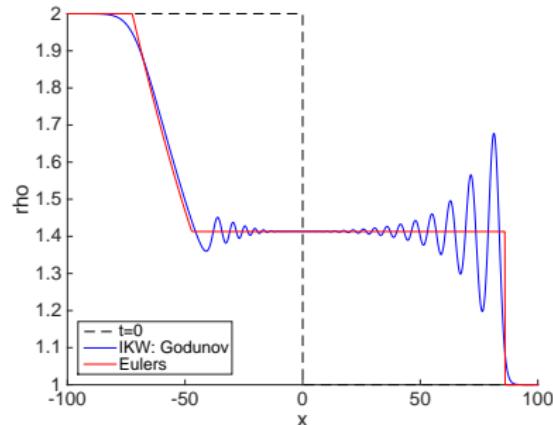
$$\partial_t (\rho K) + \partial_x (\rho K u + p_g (R)) = \partial_x \left(\frac{a^2 \rho_l}{18 \rho^3 R^4} (\partial_x u)^2 \right)$$

with generalized velocity K defined by

$$K = u - \partial_x \left(\frac{a \rho_l}{3 \rho R} \partial_x u \right).$$

Here $\rho = \alpha_l \rho_l + \alpha_g \rho_g$, u , p_g , R denote mixture density, velocity, gas pressure, & bubble radius, respectively. Variables α_k & ρ_k are in turn volume fraction & phasic density of fluid phase k for $k = l$ (liquid phase), g (gas phase); $\alpha_l + \alpha_g = 1$

Dambreak problem: IKW model



Thank you